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# Selection of mixed sampling plan with QSS-1(n; $c_N,c_T$ ) plan as attribute plan indexed through MAPD and AQL

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### Abstract

This paper presents the procedure for the construction and selection of the mixed sampling plan using MAPD as a quality standard with the QSS-1 ( $n_{;}c_{N_{,}}c_{T}$ ) plan as attribute plan. The plans indexed through MAPD and AQL are constructed and compared for their efficiency. Tables are constructed for easy selection of the plan.

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### Keywords: QSS-1, MAPD, AQL, Mixed sampling plan.

Introduction Mixed sampling plans consist of two stages of rather different nature. During the first stage the given lot is considered as a sample from the respective production process and a criterion by variables is used to check process quality. If process quality is judged to be sufficiently good, the lot is accepted. Otherwise the second stage of the sampling plan is entered and lot quality is checked directly by means of an attribute sampling plan.

There are two types of mixed sampling plans called independent and dependent plans. If the first stage, sample results are not utilized in the second stage, then the plan is said to be independent otherwise dependent. The principal advantage of a mixed sampling plan over pure attribute sampling plans is a reduction in sample size for a similar amount of protection.

Schilling (1967) proposed a method for determining the operating characteristics of mixed variables-attributes sampling plans, single sided specification and standard deviation known using the normal approximation. Devaarul, 2003, Sampath Kumar, 2007, Radhakrishnan & Sampath Kumar, 2006a, 2006b, 2007a, 2007b and 2009 have made contributions to mixed sampling plans for independent case (Radhakrishnan *et al.*, 2009).

Dodge (1967) proposed a new sampling system consisting of pairs of normal and tightened plans. Romboski (1969) has developed QSS by attributes is a reduction in the sample size required to achieve approximately the same operating characteristic curve. In this study, using the operating procedure of mixed sampling plan with QSS-1 ( $n;c_N,c_T$ ) plan as attribute plan, tables are constructed for the mixed sampling plan indexed through (i) MAPD (ii) AQL (acceptable quality level). This plan indexed through MAPD is compared with the plan indexed through AQL. Suitable suggestions are also provided for future research.

#### Conditions of applications of QSS-1-Mixed sampling plan

- The production is steady so that results on current and preceding lots are broadly indicative of a continuing process.
- Lots are submitted substantially in the order of their production.

• The inspection involves costly or destructive tests such that normally only a small number of tests per lot can be justified.

### Glossary of symbols

The symbols used in this paper are as follows:

p : submitted quality of lot or process

P<sub>a</sub> (p) : probability of acceptance for given quality 'p'

 $p_1$  : the submitted quality such that  $P_a$  ( $p_1$ ) = 0.95 (also called AQL)

- p. : maximum allowable percent defective (MAPD)
- h. : relative slope at 'p.'
- n<sub>1</sub> : sample size of variable sampling plan
- n<sub>2</sub> : sample size of attribute sampling plan
- c<sub>N</sub> : acceptance number of normal inspection
- c<sub>T</sub> : acceptance number of tightened inspection
  - : probability of acceptance for lot quality 'p'

 $\hat{\beta}'_{j}$ : probability of acceptance assigned to first stage for percent defective 'p<sub>i</sub>'

 $\beta_j$ ": probability of acceptance assigned to second stage for percent defective ' $p_i$ '

d : observed number of nonconforming units in a sample of n units

z(j) : 'z' value for the j<sup>th</sup> ordered observation

k : variable factor such that a lot is accepted if  $\overline{X} \leq$  A = U - k  $\sigma$ 

# Operating procedure of mixed sampling plan with QSS- $1(n;c_N,c_T)$ as attribute plan

Schilling (1967) has given the following procedure for the independent mixed sampling plan with Upper specification limit (U) and known standard **deviation** (**o**).

• Determine the parameters of the mixed sampling plan  $n_1$ ,  $n_2$ , k,  $c_N$  and  $c_T$ .

- Take a random sample of size n<sub>1</sub> from the lot.
- If a sample average  $\overline{X} \leq A = U k\sigma$ , accept the lot.
- If a sample average  $\overline{X} > A = U k\sigma$ , go to step 1.

**Step 1:** From a lot, take a random sample of size  $n_2$  at the normal level. Count the number of defectives 'd'

- If  $d \le c_N$ , accept the lot and repeat step 1.
- If  $d > c_N$ , reject the lot and go to step 2.



• If  $d \le c_T$ , accept the lot and use step 1 for the next lot.

• If  $d > c_T$ , reject the lot and repeat step 2 for the next lot.

## Construction of mixed sampling plan having QSS-1(n; $c_N,c_T$ ) as attribute plan

The operation of mixed sampling plans can be properly assessed by the OC curve for given values of the fraction defective. The development of mixed sampling plans and the subsequent discussions are limited only to the upper specification limit 'U'. A parallel discussion can be made for lower specification limits.

The procedure for the construction of mixed sampling plans is provided by Schilling (1967) for a given ' $n_1$ ' and a point ' $p_i$ ' on the OC curve is given below.

• Assume that the mixed sampling plan is independent

• Split the probability of acceptance  $(\beta_j)$  determining the probability of acceptance that will be assigned to the first stage. Let it be  $\beta_i$ '.

 $\bullet$  Decide the sample size  $n_1$  (for variable sampling plan) to be used

• Calculate the acceptance limit for the variable sampling plan as

A = U - k $\sigma$  = U - [z (p<sub>j</sub>) + {z (β<sub>j</sub>')/ $\sqrt{n_1}$  }] $\sigma$ , where U is the upper specification limit and z(t) is the standard normal variate corresponding to 't' such that

$$t = \int_{z(t)}^{\infty} \frac{1}{\sqrt{2\pi}} e^{-u^2/2} du$$

• Determine the sample average  $\overline{X}$ . If a sample average  $\overline{X} > A = U - k\sigma$ , take a second stage sample of size 'n<sub>2</sub>' using attribute sampling plan.

• Split the probability of acceptance  $\beta_j$  as  $\beta_j'$  and  $\beta_j''$ , such that  $\beta_j = \beta_j' + (1 - \beta_j') \beta_j''$ . Fix the value of  $\beta_j'$ .

• Now determine  $\beta_j$ ", the probability of acceptance assigned to the attributes plan associated with the second stage sample as  $\beta_i$ " = ( $\beta_i - \beta_i$ ) / (1- $\beta_i$ )

- Determine the appropriate second stage sample of size  $\mathsf{'}n_2\mathsf{'}$  from

Pa (p) =  $\beta_i$ " for p =  $p_i$ .

Using the above procedure tables can be constructed to facilitate easy selection of mixed sampling plan with QSS-1( $n;c_N,c_T$ ) plan as attribute plan indexed through MAPD and AQL.

According to Soundararajan and Arumainayagam (1988), the operating characteristic function of QSS-1 is given below.

$$P_{a}(p) = \frac{b}{1-a+b}$$
(1)  
Where

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$$a = \sum_{i=0}^{c_N} \frac{e^{-n_2 p} (n_2 p)^i}{i!}$$
(2)

$$b = \sum_{j=0}^{c_T} \frac{e^{-n_2 p} (n_2 p)^j}{j!}$$
(3)

(for acceptance number tightening) Construction of the plans indexed through MAPD

MAPD (p-), introduced by Mayer (1967) and further studied by Soundararajan (1975) is the quality level corresponding to the inflection point of the OC curve. The degree of sharpness of inspection about this quality level 'p-' is measured by 'p<sub>t</sub>', the point at which the tangent to the OC curve at the inflection point cuts the proportion defective axis. For designing, Soundararajan (1975) proposed a selection procedure for mixed sampling plan indexed with MAPD and  $K = p_t / p_{-}$ .

Using the probability mass function of QSS-1, given in expression (1) , the inflection point (p-) is obtained by

using 
$$\frac{d^2 p_a(p)}{dp^2} = 0$$
 and  $\frac{d^3 p_a(p)}{dp^3} \neq 0$ . The relative

slope of the OC curve  $h_{+} = \left[\frac{-p}{p_a(p)}\right] \frac{dp_a(p)}{dp}$  at  $p = p_{+}$ .

The inflection tangent of the OC curve cuts the 'p' axis at  $p_t = p_* + (p_*/h_*)$ . The values of  $n_2p_*$ ,  $h_*$ ,  $n_2p_t$  and  $R = p_t/p_*$  are calculated for different values of 'c<sub>N</sub>' and 'c<sub>T</sub>' for  $\beta_*$ ' = 0.40 using c++ program and presented in Table 1. Selection of the plan

For the given values of p- and p<sub>t</sub>, the ratio R =  $\frac{p_t}{p_*}$  is found

and the nearest value of R is located in Table 1.The corresponding value of  $c_N$  ,  $c_T$  and  $np_{\text{-}}$  values are noted

and the value of  $n_2$  is obtained using  $n_2 = \frac{n_2 p_*}{p_*}$ .

Example 1: Given  $p_{\text{*}}$  = 0.048,  $p_{t}$  = 0.056 and  $\beta_{\text{*}}{}^{\prime}$  = 0.40, the

ratio R =  $\frac{p_t}{p_*}$  = 1.1667. In Table 1, the nearest R value is

1.1678 which is corresponding to  $c_N = 7$  and  $c_T = 1$ . The value of  $n_2p_* = 4.9071$  is found and hence the value of  $n_2$  is determined as  $n_2 = \frac{n_2 p_*}{p_*} = \frac{4.9071}{0.048} = 102$ . Thus  $n_2 = \frac{n_2 p_*}{p_*} = \frac{4.9071}{0.048} = 102$ .

102,  $c_N = 7$  and  $c_T = 1$  are the parameters selected for the mixed sampling plan having QSS-1(n; $c_N$ , $c_T$ ) as attribute plan using Poisson Distribution as a baseline distribution, for the given values of  $p_r = 0.048$  and  $p_t = 0.056$ .

Construction of mixed sampling plan indexed through AQL

The procedure given in Section 5 is used for constructing the mixed sampling plan indexed through AQL ( $p_1$ ). By assuming the probability of acceptance of the lot be  $\beta_1 = 0.95$  and  $\beta_1' = 0.40$ , the  $n_2p_1$  values are

"Mixed sampling" http://www.indjst.org



#### Indian Journal of Science and Technology *Table 1. Various characteristics of the mixed sampling plan when* $\beta$ *'*=

 $\beta_1 = 0.40$  and  $\beta_1 = 0.95$ 

C <sub>N</sub>	$C_T$	n <sub>2</sub> p <sub>1</sub>	β∗"	n₂p∗	h∗	n <sub>2</sub> pt	R=pt/p∗
1	0	0.3980	0.4703	1.2027	1.3173	2.1157	1.7591
2	1	0.9364	0.4018	2.4499	1.8970	3.7414	1.5272
3	2	1.5517	0.3670	3.6731	2.3486	5.2371	1.4258
3	1	1.4003	0.3435	3.0552	2.7412	4.1697	1.3648
3	0	1.1424	0.3298	2.3076	3.1052	3.0507	1.3220
2	0	0.7636	0.3752	2.5374	3.3547	3.2938	1.2981
6	5	3.6356	0.3175	7.2334	3.3768	9.3754	1.2961
5	3	2.7790	0.3107	5.4446	3.4962	7.0019	1.2860
7	6	4.3782	0.3072	8.4020	3.6660	10.6939	1.2728
6	4	3.5066	0.3005	6.6147	3.8117	8.3501	1.2624
4	0	1.5249	0.3008	0.7632	3.9511	3.4625	1.2531
6	3	3.3204	0.2890	5.9433	4.2453	7.3433	1.2356
5	1	2.3011	0.2887	4.0321	4.3526	4.9585	1.2298
9	7	5.7893	0.2800	10.0683	4.6228	12.2463	1.2163
6	2	3.0684	0.2800	5.2355	4.6936	6.3510	1.2131
5	0	1.9083	0.2813	3.1942	4.7855	3.8617	1.2090
9	6	5.6252	0.2708	9.3999	5.0701	11.2539	1.1972
6	1	2.7380	0.2728	4.4768	5.1543	5.3454	1.1940
8	4	4.6231	0.2680	7.5679	5.2755	9.0024	1.1896
9	5	5.4134	0.2633	8.7155	5.5358	10.2899	1.1806
8	3	4.3456	0.2615	6.8583	5.7555	8.0499	1.1737
7	1	3.1675	0.2607	4.9071	5.9578	5.7307	1.1678
8	2	4.0063	0.2560	6.1188	6.2526	7.0974	1.1599
7	0	2.6741	0.2558	4.0191	6.4464	4.6426	1.1551
8	1	3.5910	0.2527	5.3229	6.7489	6.1116	1.1482
9	2	4.4600	0.2475	6.5453	7.0404	7.4750	1.1420
9	1	4.0095	0.2435	5.7411	7.5711	6.4994	1.1321
9	0	3.4370	0.2388	4.8192	8.1148	5.4131	1.1232
11	2	5.3451	0.2348	7.3796	8.6271	8.2350	1.1159
11	1	4.8341	0.2725	6.4360	8.6900	7.1766	1.1151
12	0	4.5763	0.2347	5.9614	10.4466	6.5321	1.0957

Table 2. Comparison of plans indexed through MAPD and AQL

p*	pt	сN	сТ	Indexed through MAPD	Indexed through AQL
				n2	n2
0.027*	0.033	5	1	149	164
0.047	0.054	8	1	113	121
0.052	0.065	4	0	53	59
0.059	0.078	3	0	39	44

\*OC curves is drawn

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calculated for different values of ' $c_N$ ' and ' $c_T$ ' using c++ program and is presented in Table 1. Selection of the plan

Table 1 is used to construct the plans when AQL (p<sub>1</sub>), 'c<sub>N</sub>' and 'c<sub>T</sub>' are given. For any given values of p<sub>1</sub>,' c<sub>N</sub>' and 'c<sub>T</sub>' one can determine n<sub>2</sub> value using  $n_2 = \frac{n_2 p_1}{n_1}$ .

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Example 2: Given  $p_1 = 0.04$ ,  $c_N = 9$  and  $c_T = 6$  and

 $\beta_1' = 0.40$ . Using Table 1, find  $n_2 = \frac{n_2 p_1}{p_1} =$ 

 $\frac{5.6252}{0.04}$  = 141. Thus  $n_2$  = 141,  $c_N$  = 9 and  $c_T$  = 6

are the parameters selected for the mixed sampling plan having QSS-1( $n;c_N,c_T$ ) as attribute plan for a specified  $p_1 = 0.04$ ,  $c_N = 9$  and  $c_T = 6$ Comparison of mixed sampling plan indexed through MAPD and AQL



In this section mixed sampling plan indexed through MAPD is compared with mixed sampling plan indexed through AQL by fixing the parameters  $c_N$ ,  $c_T$  and  $\beta_j'$ . For the specified values of p- and  $p_t$  with the assumption  $\beta$ -' = 0.40, one can find the values of  $c_N$ ,  $c_T$  and  $n_2$  indexed through MAPD. By fixing the values of  $c_N$  and  $c_T$ , find the value of  $p_1$  by equating Pa (p) =  $\beta_1$  = 0.95. Using  $\beta_1$ ' = 0.40,  $c_N$  and  $c_T$  one can find the value of  $n_2$  using  $n_2 = \frac{n_2 p_1}{r_1}$  from Table 1. For different

combinations of  $p_{+}, p_{t}, c_{N}$  and  $c_{T}$  the values of  $n_{2}$  (indexed through MAPD) and  $n_{2}$  (indexed through AQL) are calculated and presented in Table 2.

 $p_1$ 

Construction of OC curve

probability of acceptance

The OC curves for the plans  $n_2 = 149$ ,  $c_N = 5$ ,  $c_T = 1$  (indexed through MAPD) and  $n_2 = 164$ ,  $c_N = 5$ ,  $c_T = 1$  (indexed through AQL) based on the different values of  $n_2p_1$  and  $p_a(p)$  are presented in Fig.1.

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### Conclusion

In this paper, using the operating procedure of mixed sampling plan with QSS-1(n; $c_N$ , $c_T$ ) as attribute plan, tables are constructed for the mixed sampling plan indexed through the parameters MAPD and AQL by taking Poisson distribution as a baseline distribution. It is concluded from the study that the second stage sample size required for QSS-1( $n_{c_N,c_T}$ ) plan indexed through MAPD is less than that of the second stage sample size of the QSS-1( $n;c_N,c_T$ ) plan indexed through AQL. Examples are provided for a specified value of  $\beta_i' = 0.40$ . If the floor engineers know the levels of MAPD or AQL, they can have their sampling plans on the floor itself by referring to the tables. This provides the flexibility to the floor engineers in deciding their sampling plans. Various plans can also be constructed to make the system user friendly by changing the first stage probabilities ( $\beta_{+}$ ',  $\beta_{1}$ ') and can also be compared for their efficiency.

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